

**APPENDIX**  
**VERSION WITH MARKINGS TO SHOW CHANGES MADE**

The paragraph beginning on line 16 of page 3 was replaced with the following:

Conventionally, increasing the throughput requirements of a reticle scanning stage may cause the accuracy associated with the reticle scanning stage to be compromised, as actuators which are capable of higher accelerations are generally more difficult to control and, hence, less accurate. In addition to being less accurate, it is also difficult to position large actuators such that a line of force associated with the actuators may cross through the center of [a reticle] gravity. When the line of force is not through the center of gravity of the fine stage, then a substantial "balancing mass" is required to balance the overall stage. The use of such a balancing mass may further increase the size of the overall stage. To increase the accuracy associated with a reticle scanning stage and to substantially minimize the size of the reticle scanning stage, smaller, more controllable actuators may be used with the reticle scanning stage, at the expense of acceleration capabilities.

The paragraph beginning on line 16 of page 8 was replaced with the following:

Fig. 5b is a diagrammatic representation of a coarse stage and a fine stage, *i.e.*, coarse stage 506 and fine stage 510 of Fig. 5a, when the coarse stage is [accelerating] either moving at a constant velocity in a positive y-direction or in a stationary position in accordance with an embodiment of the present invention.